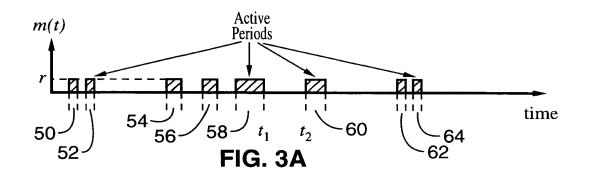
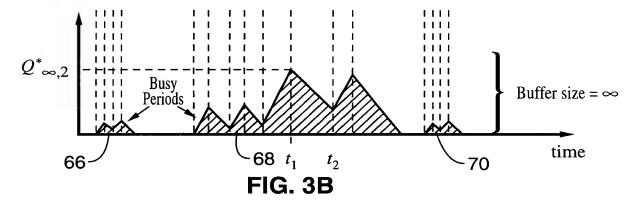
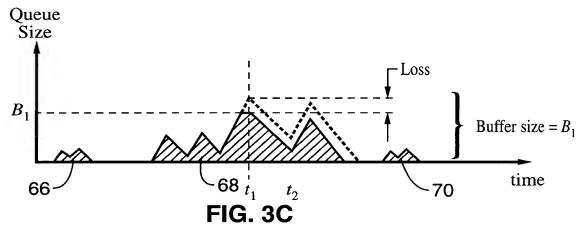
. Б Е

```
/* Index i denotes the i-th frame, q_i denotes the queue size at the instant
 just after the i-th frame arrival and index j denotes the j-th active period. */
1 /* Perform initialization */
1.1 s_1^r \leftarrow 1/f; q_1 \leftarrow d_1; i \leftarrow j \leftarrow 1;
2.1 If ((q_i)/(r)) < \frac{1}{f} /* no backlog present at the start of next frame */
2.1.1 q_{i+1} \leftarrow d_{i+1};
2.1.2 t_i^r \leftarrow \frac{1}{f} + [(q_i)/(r)]; /* compute end time of current active period */
2.1.3 j \leftarrow j+1;
2.1.4 s_i^r \leftarrow [(i+1)/(f)]; /* start time of new active period */
2.2 else
2.2.1 q_{i+1} \leftarrow q_i + d_{i+1} - {}^{r}/{}_{f_i} /* there is backlog carried to current frame */.
3
3.1 i \leftarrow i+1;
3.2 If (i < N)
3.2.1 goto Step 2;
3.3 endif
4.1 s(r) \leftarrow \max_{1 \le k} \le N q_k; /* compute maximum queue length observed */
4.2 t_i^r \leftarrow {}^{N}/{}_{f} + [(q_N)/(r)]; /* compute end time of last active period */
4.3 n_a(r) \leftarrow j; /* store the number of active periods */
4.4 Define s_{na(r)+1} = \infty;
```

FIG. 2







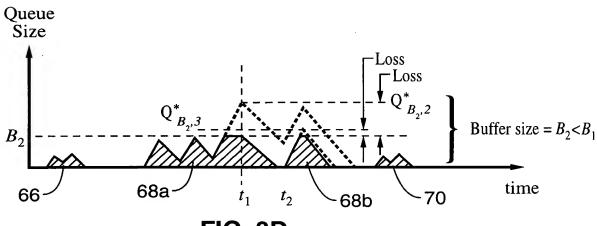
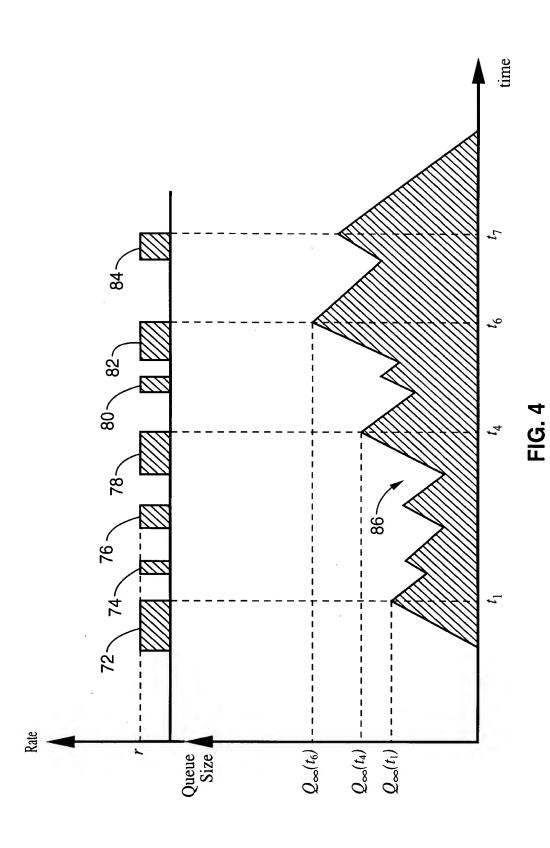


FIG. 3D



```
/* INIT. B holds the available buffer, L<sub>B</sub> holds the sum of the unrestricted queue sizes of
the busy
periods with loss at the time instants at which the maximum queue occurs, n_l holds the number
   of busy periods with loss, n_b the number of busy periods, and n_a the number of active periods.*/
 1.1 B \leftarrow \infty; L_B \leftarrow 0; n_l \leftarrow 0; M \leftarrow \text{stream\_size};
 /* Compute busy periods for rate \rho, and buffer size B. */
 1.2 process_active_periods(1, n_a, B);
 /* Insert into the heap the buffer point at which a loss occurs
    for each busy period, compute the buffer size for the first break for
   each busy period and insert it into the heap as well. */
 1.3 For b = 1 to n_b /* for each busy period b */
 1.3.1 heap_insert(Q_b, LOSS, b);
 1.3.2 B' \leftarrow \text{compute next break}(b);
 1.3.3 heap insert(B', BREAK, b);
 1.4 endfor
2 /* Extract the maximum buffer from the heap, and process
    the corresponding busy period until the heap becomes empty. */
2.1 (b, B, cause) \leftarrow heap\_extract\_max();
 /* Let (s_p, t_p), (s_{p+1}, t_{p+1}), ..., (s_q, t_q) be the active periods contained within the busy period b.
   Also, let (s_p, t_p), ..., (s_i, t_i) be the active periods contained within the interval (\alpha_b, \tau_b). */
 2.2 If (cause = LOSS)
 /* update n_l and L_R variables */
2.2.1 L_B \leftarrow L_B + (\Sigma_i = p^j r(t_i - s_i) - P(t_j - s_p));
 2.2.2 n_l \leftarrow n_l + 1;
 2.3 else /* cause = BREAK */
 /* update n_l and L_B variables */
 2.3.1 L_B \leftarrow L_B - (\Sigma_i = p^i r(t_i - s_i) - P(t_i - s_p));
 2.3.2 n_l \leftarrow n_{l-1};
  /* Process the break in busy period b: Compute the new busy periods, and update n_l and L_R
    when a busy period already experiences loss. For the remaining new busy periods, insert
    into the heap the buffer points at which the first losses occur. Finally, for all the new
    busy periods, compute the buffer sizes for the first break and insert them into the heap. */
 2.3.3 process_break(b, B);
2.4 endif
2.5 output_point(B, [(L_B-n_l B)/(M)]);
 2.6 If (heap not empty)
 2.6.1 goto Step 2;
 2.7 endif
 /* Output the last point of the loss curve */
 2.8 Output (0, [(r - P)/(r)]);
 2.9 STOP;
```

FIG. 5

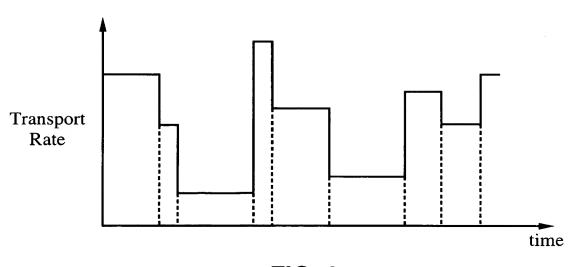


FIG. 6

